

RELEASE NOTES

Document revision: A

November 3, 2022

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Make sure that the firmware of your robot is the one indicated on the cover of this manual, or else consult the manual corresponding to your robot's firmware. Ideally, always use the latest robot firmware.

If you have any technical questions, please use the technical support form on our web site (<http://mecademic.com/contact-technical-support>).

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Version 9.2.2

Fixed

- (ROBOT-2421) Brakes are not always engaged at full strength when drives are deactivated or brakes are re-engaged manually.

Version 9.2.1

Features

- (ROBOT-1063) Support for Meca500 revision 4 robots.
- (ROBOT-2271) Support for EStop without rebooting the robot (on Meca500 revision 4+ only).
- (ROBOT-2308) Homing the robot is now required once after boot-up.
- (ROBOT-2360) Prevent writing to permanent storage during bootup if not required.
- (ROBOT-2372) Reduce velocity effects on gripper force.
- (ROBOT-1568) Added the command LogUserCommands to enable/disable the logging of user commands.